

MLFB-Ordering data

6SL3210-1KE23-8AF1



Client order no. : Order no. : Offer no. :

Remarks:

Item no. : Consignment no. : Project :

Rated data			
Input			
Number of phases	3 AC		
Line voltage	380 480 V +10 % -20 %		
Line frequency	47 63 Hz		
Rated current (LO)	48.20 A		
Rated current (HO)	45.20 A		
Output			
Number of phases	3 AC		
Rated voltage	400 V		
Rated power IEC 400V (LO)	18.50 kW		
Rated power NEC 480V (LO)	25.00 hp		
Rated power IEC 400V (HO)	15.00 kW		
Rated power NEC 480V (HO)	20.00 hp		
Rated current (IN)	38.00 A		
Rated current (LO)	37.00 A		
Rated current (HO)	31.00 A		
Max. output current	62.00 A		
Pulse frequency	4 kHz		
Output frequency for vector control	0 240 Hz		
Output frequency for V/f control	0 550 Hz		

Overload capability

Low Overload (LO)

 $150\ \%$ base load current IL for 3 s, followed by $110\ \%$ base load current IL for 57 s in a $300\ s$ cycle time

High Overload (HO)

 $200\,\%$ base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
Power factor λ	0.70 0.85		
Tower factor A	0.70 0.03		
Offset factor cos φ	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	66 dB		
Power loss	0.50 kW		
Filter class (integrated)	Class A		

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.018 m³/s (0.636 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

95 % At 40 °C (104 °F), condensation and icing not permissible

Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		
Vector control, with sensor	No		
Encoderless torque control	No		
Torque control, with encoder	No		



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		Figu	
data	Com	nmunication	
IP20 / UL open type	Communication	PROFINET / EtherNet/IP	
FSC	Connections		
4.40 kg (9.70 lb)	Signal cable		
140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWC	
295 mm (11.61 in)	Line side		
208 mm (8.19 in)	Version	Plug-in screw terminals	
puts	Conductor cross-section	6.00 16.00 mm² (AWG 10 AW	
	Motor end		
6	Version	Plug-in screw terminals	
11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AW	
5 V	DC link (for braking resistor)	
15 mA	Version	Plug-in screw terminals	
		6.00 16.00 mm² (AWG 10 AW	
1		15 m (49.21 ft)	
	-	On housing with M4 screw	
1	Max. motor cable length	Off flousing with M4 screw	
DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
1	Unshielded	150 m (492.13 ft)	
DC 30 V, 0.5 A	Standards		
	Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
1 (Differential input)		02, 002, 02, 0 Han (Ham)	
10 bit	CE marking	EMC Directive 2004/108/EC, Low-V Directive 2006/95/EC	
out			
4 V			
1.61/			
1.6 V			
	IP20 / UL open type FSC 4.40 kg (9.70 lb) 140 mm (5.51 in) 295 mm (11.61 in) 208 mm (8.19 in) Eputs 6 11 V 5 V 15 mA 1 DC 30 V, 0.5 A 1 (Differential input) 10 bit Dut 4 V	FSC Communication FSC Signal cable 4.40 kg (9.70 lb) Signal cable 140 mm (5.51 in) Conductor cross-section 295 mm (11.61 in) Line side 208 mm (8.19 in) Version Conductor cross-section Motor end Version 11 V Conductor cross-section DC link (for braking resistor) Version Conductor cross-section Line length, max. PE connection Max. motor cable length DC 30 V, 0.5 A Shielded Unshielded DC 30 V, 0.5 A Sompliance with standards 1 (Differential input) 10 bit CE marking	

PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)



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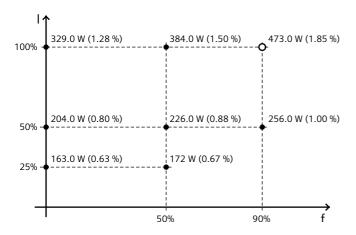
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-63.37 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values