## SIEMENS

## Data sheet

## 6ES7510-1SJ01-0AB0



SIMATIC DP, CPU 1510SP F-1 PN for ET 200SP, Central processing unit with Work memory 150 KB for program and 750 KB for data, 1st interface: PROFINET IRT with 3-port switch, 72 ns bit performance, SIMATIC Memory Card required, BusAdapter required for Port 1 and 2

General information	
Product type designation	CPU 1510SP F-1 PN
HW functional status	FS05
Firmware version	V2.9
Product function	
• I&M data	Yes; I&M0 to I&M3
<ul> <li>Module swapping during operation (hot swapping)</li> </ul>	Yes; Multi-hot swapping
Isochronous mode	Yes; Only with PROFINET; with minimum OB 6x cycle of 625 $\mu s$
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V17 (FW V2.9) / V13 SP1 Update 4 (FW V1.8) or higher
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms
Input current	
Current consumption (rated value)	0.6 A
Current consumption, max.	0.9 A
Inrush current, max.	4.7 A; Rated value
<sup>2</sup> t	0.14 A <sup>2</sup> ·s
Power	
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	5.6 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
<ul> <li>integrated (for program)</li> </ul>	150 kbyte
<ul> <li>integrated (for data)</li> </ul>	750 kbyte
Load memory	
<ul> <li>Plug-in (SIMATIC Memory Card), max.</li> </ul>	32 Gbyte

Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	72 ns
for word operations, typ.	86 ns
for fixed point arithmetic, typ.	115 ns
for floating point arithmetic, typ.	461 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the
	user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	750 kbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	750 kbyte, 1 or 205 with absolute addressing, the max. Size is 64 Kb
Number range	0 65 535
Size, max.	
	100 kbyte
FC	0 65 525
Number range	0 65 535
• Size, max.	100 kbyte
OB	
• Size, max.	150 kbyte
<ul> <li>Number of free cycle OBs</li> </ul>	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
<ul> <li>Number of delay alarm OBs</li> </ul>	20
Number of cyclic interrupt OBs	20; With Failsafe, two RTGs with one "Cyclic interrupt OB" or one "Free cycle OB" (F-OB) each are possible
<ul> <li>Number of process alarm OBs</li> </ul>	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24; Up to 8 possible for F-blocks
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
	Any (only limited by the main memory)
Retentivity	Vec
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	128 kbyte; Available retentive memory for bit memories, timers,
	counters, DBs, and technology data (axes): 88 KB
Flag	
• Size, max.	16 kbyte
<ul> <li>Number of clock memories</li> </ul>	8; 8 clock memory bit, grouped into one clock memory byte

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Data blocks	
<ul> <li>Retentivity adjustable</li> </ul>	Yes
Retentivity preset	No
Local data	
<ul> <li>per priority class, max.</li> </ul>	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	1 024; max. number of modules / submodules
I/O address area	
Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	oz koyte, Ali odiputo are in the process image
	9 khyta
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
<ul> <li>Number of subprocess images, max.</li> </ul>	32
Address space per module	
<ul> <li>Address space per module, max.</li> </ul>	288 byte; For input and output data respectively
Address space per station	
<ul> <li>Address space per station, max.</li> </ul>	2 560 byte; for central inputs and outputs; depending on configuration; 2
	048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration
	of distributed I/O via PROFINET or PROFIBUS communication
	modules, but also by the connection of I/O via AS-i master modules or
	links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
<ul> <li>integrated</li> </ul>	1
• Via CM	0
Rack	
<ul> <li>Modules per rack, max.</li> </ul>	80; CPU + 64 modules + server module (mounting width max. 1 m) + 16
	ET 200AL modules
<ul> <li>Quantity of operable ET 200SP modules, max.</li> </ul>	64
<ul> <li>Quantity of operable ET 200AL modules, max.</li> </ul>	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of
	available slots
Time of day	
Clock	
• Туре	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• to DP, slave	Yes; Via CM DP module
• in AS, master	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Optical interface	No
	No

Interface types	
RJ 45 (Ethernet)	Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Number of ports	3; 1. integr. + 2. via BusAdapter
integrated switch	Yes
BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x FC, BA 2x M12
Protocols	Tes, compatible bushdapters. DA 2x N343, DA 2x T C, DA 2x M12
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0
PROFINET IO Controller	Tes, Mixir Automanager according to IEC 02439-2 Edition 2.0
Services	
— PG/OP communication	Yes
— Isochronous mode	Yes
<ul> <li>Direct data exchange</li> </ul>	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— Direct data exchange — IRT	Yes
— PROFlenergy	Yes; per user program
— Pronenergy     — Prioritized startup	Yes; Max. 32 PROFINET devices
— Phonized startup     — Number of connectable IO Devices, max.	64; In total, up to 256 distributed I/O devices can be connected via AS-i,
	PROFIBUS or PROFINET
— Of which IO devices with IRT, max.	64
<ul> <li>— Number of connectable IO Devices for RT, max.</li> </ul>	64
— of which in line, max.	64
— Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	
— Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication
	share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	250 $\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 $\mu s$ of the isochronous OB is decisive
— for send cycle of 500 μs	500 $\mu s$ to 8 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 $\mu s$ of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul> <li>— With IRT and parameterization of "odd" send</li> </ul>	Update time = set "odd" send clock (any multiple of 125 µs: 375 µs, 625
cycles	μs 3 875 μs)
Update time for RT	
— for send cycle of 250 µs	250 µs to 128 ms
— for send cycle of 500 µs	500 µs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	N .
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
<ul> <li>— Number of IO Controllers with shared device, max.</li> </ul>	4
- activation/deactivation of I-devices	Yes; per user program
<ul> <li>Asset management record</li> </ul>	Yes; per user program
2. Interface	
Interface types	

• RS 485	Yes; Via CM DP module
Number of ports	1
Protocols	
PROFIBUS DP master	Yes
<ul> <li>PROFIBUS DP slave</li> </ul>	Yes
<ul> <li>SIMATIC communication</li> </ul>	Yes
PROFIBUS DP master	
<ul> <li>Number of connections, max.</li> </ul>	48; Of which 4 each reserved for ES and HMI
Number of DP slaves, max.	125; In total, up to 256 distributed I/O devices can be connected via AS- i, PROFIBUS or PROFINET
Services	
— PG/OP communication	Yes
— Equidistance	No
— Isochronous mode	No
<ul> <li>Activation/deactivation of DP slaves</li> </ul>	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	Yes; V2.4 / V2.6
Number of connections	
Number of connections, max.	96; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections, max.     Number of connections reserved for ES/HMI/web	10
	64
Number of connections via integrated interfaces	32
<ul> <li>Number of connections per CP/CM</li> <li>Number of S7 routing paths</li> </ul>	16
	10
Redundancy mode	Yes
H-Sync forwarding Media redundancy	res
•	Yes; only via BusAdapter
— Media redundancy	
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
— MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
— Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
- Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
S7 routing	Yes
Data record routing	Yes
• S7 communication, as server	Yes
• S7 communication, as client	Yes
• User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
<ul> <li>— several passive connections per port, supported</li> </ul>	Yes
<ul> <li>ISO-on-TCP (RFC1006)</li> </ul>	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes

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• DCP	Yes
LLDP     Encryption	Yes Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
— Number of connections, max.	4
<ul> <li>Number of nodes of the client interfaces, max.</li> </ul>	1 000
<ul> <li>— Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max.</li> </ul>	300
<ul> <li>— Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20
<ul> <li>— Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li> </ul>	100
<ul> <li>— Number of simultaneous calls of the client instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M</li> </ul>	1
max. — Number of simultaneous calls of the client	5
instructions OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.	
<ul> <li>— Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>— Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul> <li>— Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li> </ul>	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
— Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
<ul> <li>— GDS support (certificate management)</li> <li>— Number of sessions, max.</li> </ul>	Yes 32
<ul> <li>Number of sessions, max.</li> <li>Number of accessible variables, max.</li> </ul>	52 50 000
<ul> <li>Number of registerable nodes, max.</li> </ul>	10 000
<ul> <li>Number of registerable nodes, max.</li> <li>Number of subscriptions per session, max.</li> </ul>	20
— Sampling interval, min.	100 ms
— Publishing interval, min.	500 ms
- Number of server methods, max.	20
<ul> <li>— Number of inputs/outputs per server method, max.</li> </ul>	20
— Number of monitored items, max.	1 000; for 1 s sampling interval and 1 s send interval
- Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
<ul> <li>— Number of nodes for user-defined server interfaces, max.</li> </ul>	1 000
<ul> <li>Alarms and Conditions</li> </ul>	Yes
<ul> <li>Number of program alarms</li> </ul>	100
— Number of alarms for system diagnostics	50
Further protocols	
MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes

Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm"
Number of leadable program messages in DUN mark	block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	2 500
Test commissioning functions	Vac: Parallal aplina access passible for up to 5 anginaering systems
Joint commission (Team Engineering) Status block	Yes; Parallel online access possible for up to 5 engineering systems Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	•
Status/control variable	Yes; without fail-safe
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
<ul> <li>Number of variables, max.</li> </ul>	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing	Yes; without fail-safe
<ul> <li>Forcing, variables</li> </ul>	Peripheral inputs/outputs
<ul> <li>Number of variables, max.</li> </ul>	200
Diagnostic buffer	
• present	Yes
Number of entries, max.	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED     Monitoring of the supply yeltage (DW/D LED)	Yes
<ul> <li>Monitoring of the supply voltage (PWR-LED)</li> <li>Connection display LINK TX/RX</li> </ul>	Yes
Supported technology objects	
	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects Motion Control • Number of available Motion Control resources for	Yes; Note: The number of technology objects affects the cycle time of
Supported technology objects Motion Control • Number of available Motion Control resources for technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per external encoder	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per external encoder         — per output cam	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per cam track	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per cam track         — per probe	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 40 80 160 80 20 160 40
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per cam track         — per probe	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 40 80 160 80 20 160 40
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — per probe         • Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — per forbe         • Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — per probe         • Positioning axis         — per probe         • Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID_3Step	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — per probe         • Positioning axis         — Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID_Temp	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per cam track         — per probe         • Positioning axis         — number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID-Temp         Counting and measuring	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — per cam track         — per probe         • Positioning axis         — Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID-Temp         Counting and measuring         • High-speed counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per output cam         — per probe         • Positioning axis         — per probe         • Positioning axis         — per probe         • Positioning axis         — Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID_Temp         Counting and measuring         • High-speed counter         Standards, approvals, certificates         Highest safety class achievable in safety mode         • Performance level according to ISO 13849-1	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes PLe
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — per output cam         — per probe         • Positioning axis         — Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID_Temp         Counting and measuring         • High-speed counter         Standards, approvals, certificates         Highest safety class achievable in safety mode         • Performance level according to ISO 13849-1         • SIL acc. to IEC 61508	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes
Supported technology objects         Motion Control         • Number of available Motion Control resources for technology objects         • Required Motion Control resources         — per speed-controlled axis         — per positioning axis         — per synchronous axis         — per output cam         — per probe         • Positioning axis         — Number of positioning axes at motion control cycle of 4 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         — Number of positioning axes at motion control cycle of 8 ms (typical value)         Controller         • PID_Compact         • PID-Temp         Counting and measuring         • High-speed counter         Standards, approvals, certificates         Highest safety class achievable in safety mode         • Performance level according to ISO 13849-1	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes

with SIL3 — High demand/continuous mode: PFH in accordance with SIL3	< 1.00E-09
Ambient conditions	
Ambient temperature during operation	
<ul> <li>horizontal installation, min.</li> </ul>	-25 °C; No condensation
<ul> <li>horizontal installation, max.</li> </ul>	60 °C
<ul> <li>vertical installation, min.</li> </ul>	-25 °C; No condensation
vertical installation, max.	50 °C
Altitude during operation relating to sea level	
<ul> <li>Installation altitude above sea level, max.</li> </ul>	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes; incl. failsafe
— FBD	Yes; incl. failsafe
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
<ul> <li>User program protection/password protection</li> </ul>	Yes
Copy protection	Yes
Block protection	Yes
Access protection	
<ul> <li>protection of confidential configuration data</li> </ul>	Yes
<ul> <li>Protection level: Write protection</li> </ul>	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
<ul> <li>Protection level: Write protection for Failsafe</li> </ul>	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
lower limit	adjustable minimum cycle time
upper limit	adjustable maximum cycle time
Dimensions	
Width	100 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	310 g
last modified:	4/1/2022 🖸